

IF NP LANGUAGES ARE HARD ON THE WORST-CASE, THEN IT IS EASY TO FIND THEIR HARD INSTANCES

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Abstract. We prove that if $\text{NP} \not\subseteq \text{BPP}$, i.e., if SAT is worst-case hard, then for every probabilistic polynomial-time algorithm trying to decide SAT, there exists some polynomially samplable distribution that is hard for it. That is, the algorithm often errs on inputs from this distribution. This is the first worst-case to average-case reduction for NP of any kind. We stress however, that this *does not* mean that there exists *one fixed* samplable distribution that is hard *for all* probabilistic polynomial-time algorithms, which is a pre-requisite assumption needed for one-way functions and cryptography (even if not a sufficient assumption). Nevertheless, we do show that there is a fixed distribution on instances of NP-complete languages, that is samplable in *quasi-polynomial time* and is hard for all probabilistic polynomial-time algorithms (unless NP is easy in the worst case).

Our results are based on the following lemma that may be of independent interest: Given the description of an efficient (probabilistic) algorithm that fails to solve SAT in the worst case, we can efficiently generate at most three Boolean formulae (of increasing lengths) such that the algorithm errs on at least one of them.

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1. Introduction

It is traditional in computational complexity to measure *worst-case* complexities, and say that a problem is feasible if it can be solved in worst-case polynomial time (i.e., it is in P or BPP). A general belief is that NP-complete languages do not have feasible algorithms that are correct on every input. Thus under a worst-case measure of complexity, these problems are hard. However,

this does not mean that *in practice* NP-complete problems are hard. It is possible that for a given problem, its hard instances are “rare”, and in fact it is solvable efficiently on all instances that actually appear in practice.

1.1. Average-case complexity: The cryptographic approach. This point of view led Levin (1986) to develop the theory of average-case complexity of NP problems, trying to capture the notions of easiness and hardness on the average. We now give a brief overview of the main concepts in this theory.

Let L be a language that we want to decide, and let \mathcal{D} be a distribution over the instances. Here (and throughout the paper) we think of \mathcal{D} as an ensemble of distributions $\{\mathcal{D}_n\}_{n \in \mathbb{N}}$, where \mathcal{D}_n is a distribution over $\{0, 1\}^n$.¹ We want to measure how hard it is to decide L with respect to the distribution \mathcal{D} . Thus we look at the complexity of the *distributional problem* (L, \mathcal{D}) .

Trying to capture the notion of “real-life” instances, we look at input distributions that can be efficiently generated. We say that \mathcal{D} is *samplable* if there exists some probabilistic polynomial-time machine that generates the distribution. Formally, we require that there is a probabilistic polynomial time algorithm such that the output distribution of this algorithm on input 1^n , is the distribution \mathcal{D}_n .²

This leads to a definition of the distributional analogue of the class NP.

DEFINITION 1.1. *The class $DistNP$ contains all the distributional problems (L, \mathcal{D}) , where $L \in NP$ and \mathcal{D} is a samplable distribution.*

Levin (1986) and subsequent papers (e.g., Ben-David *et al.* (1990); Gurevich (1990, 1991); Venkatesan & Levin (1988)) defined the notions of reductions between distributional problems and completeness in $DistNP$, and were able to show several complete problems in the class.

Next, we turn to define the notion of a distributional problem being “easy” on the average.

DEFINITION 1.2. *Let \mathcal{C} be a class of algorithms and (L, \mathcal{D}) a distributional problem. We say that $(L, \mathcal{D}) \in Avg_{p(n)} \mathcal{C}$ if there is an algorithm $A_D \in \mathcal{C}$ such that for every large enough n , $\Pr_{x \in \mathcal{D}_n}[A_D(x) = L(x)] \geq p(n)$.*

¹We mention that Levin considered a single distribution over all inputs, but Impagliazzo (1995) showed that it is essentially equivalent to consider ensembles of distributions.

²We remark that Levin considered a more restricted class of distributions that are P-computable, i.e., their probability function can be calculated in polynomial time. However, Impagliazzo & Levin (1990) showed that there is an average-case hard language in NP with respect to a samplable distribution if and only if there is an average-case hard language in NP with respect to a P-computable distribution.

The actual definition given in Levin (1986) differ in various details from Definition 1.2, for example whether the algorithm has a zero-sided, one-sided or two-sided error, and whether the algorithm has a strict running time or only expected running time. The definition we give here is due to Impagliazzo (1995), where it is called *Heur P*.

When thinking of efficient solutions, we should think of \mathcal{C} as being P or BPP. Thus the average-case analogue of the statement $\text{NP} \not\subseteq \text{BPP}$ (i.e., $\text{DistNP} \not\subseteq \text{AvgBPP}$) is that there exists an NP language L and a samplable distribution \mathcal{D} , such that every efficient probabilistic algorithm errs with high probability over instances drawn from \mathcal{D} .

This notion seems to capture the intuition of a problem being hard on the average. Furthermore, it seems to be the right notion of hardness that is needed for cryptographic applications. For example, consider a cryptosystem that is based on the RSA encryption scheme. We would like the user to be able to sample efficiently composite numbers of the form $N = p \cdot q$ (where p, q are prime numbers known to the user) such that with high probability over this sample space, an adversary would not be able to factor the chosen number and to break the encryption. Thus, in particular, we require a samplable distribution that together with the problem of factoring will give a distributional problem that is not in AvgBPP. We should point out though, that this requirement in itself does not suffice for this application, because we need to generate numbers according to the distribution *together with their factorization*. The point that we want to make is that for this application, average-case hardness is *necessary*.

1.2. Average-case complexity: The algorithmic approach. While the notion of hard distributional problems seems to capture the intuitive meaning of *hardness on average*, we now explain that it may be insufficient to capture the intuitive meaning of *easiness on average* and may be problematic when taking an algorithmic point of view. That is, saying that a distributional problem (L, \mathcal{D}) is easy on the average means that there is an efficient (average-case) algorithm for the specific distribution \mathcal{D} . Often, we don't have precise knowledge of the distribution of the inputs, and even worse, this distribution may change in the future. A reasonable guarantee is that the inputs are drawn from some *unknown* samplable distribution (which, as before, is our model of "real-life" instances). Thus we would like to design an algorithm that is guaranteed to succeed with good probability whenever the inputs are sampled from some samplable distribution. This gives rise to the following definition, due to Kabanets (2001).

DEFINITION 1.3 (Pseudo classes). *Let \mathcal{C} be a class of algorithms and L a language. We say that $L \in \text{Pseudo}_{p(n)} \mathcal{C}$ if there exists an algorithm $B \in \mathcal{C}$ such that for every samplable distributions $\mathcal{D} = \{\mathcal{D}_n\}_{n \in \mathbb{N}}$ we have that for large enough n , $\Pr_{x \in \mathcal{D}_n}[B(x) = L(x)] \geq p(n)$.*

When \mathcal{C} is a class of probabilistic algorithms, there are subtleties in this definition (as well as in Definition 1.2). In the introduction we ignore these subtleties and we refer the reader to Definition 2.1, which addresses these issues.

Note that if $L \subseteq \text{Pseudo}_p \mathcal{C}$ then for every samplable distribution D , $(L, D) \in \text{Avg}_p \mathcal{C}$, while the converse does not seem to hold. Definition 1.3 and its generalizations arise in the context of derandomization in the uniform setting Gutfreund *et al.* (2003); Impagliazzo & Wigderson (1998); Kabanets (2001); Lu (2001); Trevisan & Vadhan (2006) (the reader is referred to Kabanets (2002) for a recent survey). We believe this definition captures a basic notion in computational complexity. We want to mention that Trevisan & Vadhan (2006) also made the distinction between definitions of average-case complexity for “hardness” and definitions for “easiness”.

1.3. Worst-case to average-case reductions in NP. Cryptography has been a very successful field in the last few decades. A vast amount of cryptographic primitives are known to exist under complexity theoretic assumptions. Yet, the basis on which cryptography relies is much less understood.

The weakest assumption that allows cryptographic applications is the existence of one-way functions (OWF) Impagliazzo & Luby (1989). However, all the current candidate constructions of one-way functions rely on the hardness of specific problems (such as factoring, discrete log or lattice problems Ajtai (1996); Ajtai & Dwork (1997); Diffie & Hellman (1976); Micciancio & Regev (2004); Rabin (1979); Regev (2004); Rivest *et al.* (1978)). None of these problems is known to be as hard as solving an NP-complete language in the worst-case.³

The desire to make the foundations of cryptography more credible, or at least better understood, drove much work in the past, and is a question of fundamental importance. In particular it was shown that the existence of OWF is equivalent to the existence of many cryptographic primitives such as: pseudorandom generators, pseudorandom functions, bit commitments, and digital signatures Goldreich *et al.* (1986); Håstad *et al.* (1999); Impagliazzo & Luby (1989); Naor (1991); Rompel (1990).

³Some of these problems only rely on an average-case hardness assumption, and others, such as lattice based problems, rely on the worst-case hardness of languages that are unlikely to be NP-complete Aharonov & Regev (2005); Goldreich & Goldwasser (2000).

Perhaps the holy grail of the area is the attempt to base the existence of one-way functions on a worst-case computational complexity assumption, such as $\text{NP} \neq \text{P}$ or $\text{NP} \not\subseteq \text{BPP}$. One thing that is clear from the beginning is that the assumption that OWF exist, at the very least, implies that there exists a language in NP that is hard on average for BPP. Thus an important (and necessary) step towards basing cryptography on the $\text{NP} \not\subseteq \text{BPP}$ assumption is showing a worst-case to average-case reduction for an NP-complete problem.

OPEN QUESTION 1.4. *Does $\text{NP} \not\subseteq \text{BPP}$ imply $\text{DistNP} \not\subseteq \text{Avg}_{1-n^{-o(1)}} \text{BPP}$?*

Open Question 1.4 has been the focus of some recent research (the reader is referred to Bogdanov & Trevisan (2003) for more details). We note that the error parameter $n^{-O(1)}$ can be significantly improved by known hardness amplification results Healy *et al.* (2006); Impagliazzo & Levin (1990); O’Donnell (2004); Trevisan (2003, 2005). Some of the aforementioned results require hardness against circuits (rather than probabilistic polynomial time algorithms).

Worst-case to average-case reductions have been shown to exist for complete languages in high complexity classes such as EXP, PSPACE, and $\sharp\text{P}$ (where hardness is measured both against uniform and nonuniform classes) Babai *et al.* (1993); Impagliazzo & Wigderson (1997); Sudan *et al.* (2001); Trevisan & Vadhan (2006). In contrast, no worst-case to average-case reductions are known for NP-complete problems. In fact, there are results that rule out several classes of such reductions. Specifically, Bogdanov & Trevisan (2003) (improving on Feigenbaum & Fortnow (1993)) show that there is no worst-case to average-case black-box and non-adaptive reductions from an NP-complete language to itself unless the polynomial-time hierarchy collapses. By a black-box reduction we mean a polynomial-time oracle machine R , that when given an oracle that does “too well” on the average, solves the NP language on the worst case. This result shows that unless the polynomial-time hierarchy collapses there are no such reductions that make non-adaptive queries to their oracles. Viola (2004) showed that there is no *black-box* worst-case to average-case transformation that is computable within the polynomial-time hierarchy. Roughly speaking, a black-box transformation is an algorithm that transforms *any* worst-case hard problem into one that is hard on average, without relying on any specific properties of the problem.

1.4. Our results. Pseudo classes have received much less attention than average classes. In fact, most of what we know about pseudo classes are “easiness results” showing that assuming the existence of problems that are hard (in the worst case), certain randomized procedures can be derandomized “on the

average” Gutfreund *et al.* (2003); Impagliazzo & Wigderson (1998); Kabanets (2001); Lu (2001); Trevisan & Vadhan (2006). In this paper we study this notion in relation to “hardness”. Our main results are worst-case to average-case reductions for PseudoP and PseudoBPP.

THEOREM 1.5.

- (i) $NP \neq P \Rightarrow NP \not\subseteq Pseudo_{5/6} P$
- (ii) $NP \neq RP \Rightarrow NP \not\subseteq Pseudo_{97/100} BPP$.

This worst-case to average-case reduction in the algorithmic setting, stands in contrast to the failure in proving such a reduction in the cryptographic setting (for the class Avg BPP). To the best of our knowledge, it is the first worst-case to average-case reduction for NP-complete languages under a natural notion of average-case complexity. Stated in words, Theorem 1.5 says that if NP is hard on the worst case, then for any efficient algorithm trying to solve some NP-complete language, it is possible to efficiently sample instances on which the algorithm errs.

We remark that once we are able to sample hard instances for one specific NP-complete problem (say Satisfiability) then we can sample hard instances for any complete problem. This follows immediately by using many-one reductions because applying a many-one reduction on instances drawn from a samplable distribution results in another samplable distribution.

In order to establish Theorem 1.5, we prove a lemma that says that given the description of an efficient algorithm that fails to decide SAT, we can efficiently generate three Boolean formulae such that the algorithm errs on at least one of the three. We stress that the lemma does not rely on any unproven assumptions and is correct whether $NP = P$ or not.

Finally, we use Theorem 1.5 to show that there is a fixed distribution on instances of SAT (in fact every NP-complete language), that is samplable in quasi-polynomial time, and every efficient algorithm errs with non-negligible probability on instances drawn from the distribution. More formally,

THEOREM 1.6. *Let $f(n), s(n)$ be time-constructible functions such that $f(n) = n^{\omega(1)}$, and $s(n) = \omega(1)$. Then there is a distribution D that is samplable in time $f(n)$, such that for every NP-complete language L , the following holds,*

$$NP \neq RP \Rightarrow (L, D) \notin Avg_{1-1/s(n)} BPP.$$

Note that D is the same distribution for every NP-complete language. Interestingly, this distribution is very simple to describe (see the proof of Theorem 1.6 in Section 5).

1.5. Perspective: Impagliazzo’s worlds. Impagliazzo (1995) gives an enlightening survey where several scenarios regarding the existence of OWF and the NP vs. BPP question are explored. In particular he considers five possible worlds: Algorithmica (where NP problems are easy on the worst-case), Heuristica (where NP is hard in the worst-case but easy on the average), Pessiland (where NP is hard on the average, but yet there are no OWF), Minicrypt (where OWF exist, but not public-key cryptography), and Cryptomania (where there is public-key cryptography).

When describing his worlds, Impagliazzo considers Levin’s notion of average-case complexity (and its variants). However, Definition 1.3 suggests another possible world, located between Algorithmica and Heuristica, where NP problems are hard in the worst-case, but for every such problem there is an algorithm that does well on every samplable distribution. Let us call this world Super-Heuristica.

The difference between Heuristica and Super-Heuristica is that in the former, any algorithmic solution to some hard problem is bound to a specific distribution over the inputs. So if this distribution changes we have to come up with a new solution to the problem. In Super-Heuristica on the other hand, once a good heuristic for some NP-complete problem has been developed, every new problem that arises, only needs to be reduced to the original problem. Once this is done, we can forget about this problem: Hard instances for its heuristic never come up in practice, not now, nor in the future (as long as “real-life” is modeled well by samplable distributions).

Theorem 1.5 says that Super-Heuristica does not exist. That is, if an NP-complete problem has heuristic that does well on every samplable distribution, then it has an algorithm that does well on every input (or on every distribution, samplable or not). So if we believe that $\text{NP} \not\subseteq \text{BPP}$, then heuristics for NP-hard problems will always have to be bound to specific distributions.

1.6. Overview of the technique. In this section we give a high level overview of the proof of Theorem 1.5. Let us first focus on the first item. That is, we assume that $\text{NP} \neq \text{P}$ and need to show that for any deterministic algorithm BSAT there is a samplable distribution which generates hard instances for BSAT. The main step in the proof is a lemma that shows that there is a deterministic procedure R that when given as input the description of BSAT and an input n outputs at most three formulae, such that BSAT errs on at least one of the formulae (for infinitely many n). In other words, the procedure R finds instances such that one of them is hard for BSAT.

The basic idea. We now explain how to prove this lemma (the main theorem follows easily from the lemma). We know that BSAT does not solve SAT. Fix some length n on which BSAT makes an error. Our goal is to find an instance on which BSAT errs. The basic idea is to consider the following statement denoted ϕ_n : “*there exists an instance x of length n such that $BSAT(x) \neq SAT(x)$ ”.* Note that this statement is a true statement. If this statement was an NP statement then we could reduce it into an instance of SAT and feed it to BSAT. If BSAT answers ‘no’ then ϕ_n is an instance on which BSAT errs. If BSAT answers ‘yes’ then in some sense BSAT “admits” that it makes an error on inputs of length n . We can hope to use BSAT to *find* a witness x to ϕ_n and such a witness x is a formula on which BSAT errs.

Note however, that at the moment it is not necessarily the case that deciding ϕ_n is in NP. This is because it could be the case that BSAT errs only on unsatisfiable formulae. (Say for example that BSAT always answers ‘yes’.) Verifying that ϕ_n holds seems to require verifying that a given formula x is unsatisfiable.

A search algorithm. We overcome this difficulty by replacing BSAT with an algorithm SSAT that has the following properties:

1. When SSAT answers ‘yes’ then it also outputs a satisfying assignment, and in particular it never errs when it answers ‘yes’.
2. If BSAT answers ‘no’ on input x then SSAT answers ‘no’ on input x .
3. If BSAT answers ‘yes’ on input x then either SSAT answers ‘yes’ (and finds a satisfying assignment) or else SSAT outputs three formulae such that BSAT errs on at least one of them.

It is easy to construct such an algorithm SSAT by using the standard self-reducibility property of SAT. More precisely, on input x , the algorithm SSAT attempts to use BSAT to find a satisfying assignment. In every step it holds a formula x that BSAT answers ‘yes’ on. It then substitutes one variable of x to both “zero” and “one” and feeds these formulae to BSAT. If BSAT answers ‘yes’ on one of them, then the search continues on this formula. Otherwise, at least one of the answers of BSAT on x and the two derived formulae is clearly incorrect. Finally, SSAT accepts if it finds a satisfying assignment. It is easy to verify that SSAT has the properties listed above.

Finding hard instances. To find a hard instance we change ϕ_n to be the following statement: “*there exists an instance x of length n such that $SAT(x) = 1$ yet $SSAT(x) \neq \text{'yes'}$ ”.* Note that now deciding ϕ_n is in NP and therefore we can reduce it to a formula. To find hard instances we run $SSAT(\phi_n)$. There are three possibilities.

1. $SSAT$ finds three instances such that on one of them $BSAT$ errs.
2. $SSAT$ answers ‘no’, but in this case $BSAT$ answers ‘no’ and ϕ_n is a formula on which $BSAT$ errs.
3. $SSAT$ answers ‘yes’ and finds a satisfying assignment x .

It is important to stress that we’re not yet done in the third case. While we know that $SSAT$ errs on x , it’s not necessarily the case that $BSAT$ errs on x . In the third case, we run $SSAT$ on x . This time we know that the third possibility cannot occur (because we are guaranteed that $SSAT$ does not answer ‘yes’ on x) and therefore we will be able to find a hard instance.

Extending the argument to the case where $BSAT$ is randomized.

We say that a randomized algorithm *conforms* with *confidence level* $2/3$ if for every input x , either the algorithm accepts x with probability at least $2/3$ or it rejects x with probability at least $2/3$. When given such an algorithm $BSAT$ we can easily use amplification and get an algorithm \overline{BSAT} that conforms with confidence level $1 - 2^{-2n}$. As in the argument of Adelman (1978), for almost all choices of random strings u , $\overline{BSAT}(\cdot, u)$ ’s answer “captures” whether $BSAT$ accepts or rejects x . Thus, we can do the same argument as above replacing $BSAT$ with $\overline{BSAT}(\cdot, u)$ for a uniformly chosen u . We will find hard instances for $\overline{BSAT}(\cdot, u)$, and with high probability (over the choice of u) one of the instances will be a formula on which $BSAT$ errs with noticeable probability.

In general, we cannot assume that $BSAT$ conforms to some confidence level. For example, $BSAT$ is allowed to flip a coin on some instances. This means that on such instances (on which $BSAT$ is undecided) the confidence of $BSAT$ is not amplified. Thus we cannot say that (with high probability) $\overline{BSAT}(\cdot, u)$ and $BSAT$ accept the same set of inputs. To deal with such cases we need a more cumbersome case-analysis to implement the idea of the deterministic case. Specifically, we need to go over the reduction and each time state not only what happens to inputs on which $BSAT$ gives a definite answer, but also what happens to undecided inputs. This makes the proof of the randomized case more complicated than the deterministic case, and does not allow us to directly reduce the former to the latter.

1.7. Outline. We give some preliminaries in Section 2. In Section 3, we prove the first item of Theorem 1.5. In Section 4, we prove the second item of Theorem 1.5. In Section 5, we prove Theorem 1.6. We conclude with a discussion and open problems.

2. Preliminaries

We denote by $[n]$, the set $\{1, \dots, n\}$. For a set S , we write $i \in_R S$ for i being sampled from the uniform distribution over S . We use U_n to denote the uniform distribution on $\{0, 1\}^n$.

2.1. Satisfiability. There are many ways to encode formulae as binary strings. In this paper it is convenient to choose an encoding that can be padded. More precisely, if x is an encoding of ϕ then $x \circ 0^i$ is also an encoding of ϕ . This means for example that given x we can substitute some of the variables in x by constants and pad the obtained formula to the same length as x . We define $\text{SAT}(x)$ to be “1” if x encodes a satisfiable formula and zero otherwise. It is sometimes convenient to think of satisfiability as a language and we write $x \in \text{SAT}$ instead of $\text{SAT}(x) = 1$.

2.2. Samplable distributions. An ensemble of distributions \mathcal{D} is an infinite set of distributions $\{\mathcal{D}_n\}_{n \in \mathbb{N}}$, where \mathcal{D}_n is a distribution over $\{0, 1\}^n$. If A is a deterministic machine taking two inputs, $A(y; U_n)$ denotes the distribution obtained by picking x uniformly from $\{0, 1\}^n$ and evaluating $A(y; x)$. We say that $\mathcal{D} = \{\mathcal{D}_n\}$ is samplable in time $f(n)$ if there exists a machine A such that for every n , $A(1^n; U_{f(n)}) = \mathcal{D}_n$, and the running time of A is bounded by $f(n)$. If $f(n)$ is a fixed polynomial we simply say that \mathcal{D} is *samplable*.

2.3. The class Pseudo BPP. Let PPM denote the class of probabilistic machines that run in strict polynomial time. We define:

DEFINITION 2.1 (Pseudo BPP). *We say that $L \in \text{Pseudo}_{p(n)} \text{BPP}$ if there exists a PPM algorithm B such that for every samplable distributions $\mathcal{D} = \{\mathcal{D}_n\}_{n \in \mathbb{N}}$ we have that for large enough n , $\Pr_{x \in \mathcal{D}_n, y \in_R \{0, 1\}^r} [B(x, y) = L(x)] \geq p(n)$.*

2.4. Confidence level of probabilistic machines. It is convenient to associate some *deterministic function* with any probabilistic machine by requiring that the machine accepts/rejects with some *confidence level*. More precisely, a confidence level is a function $c(n)$ over integers, such that for every

n , $1/2 < c(n) \leq 1$. Given a machine $M \in \text{PPM}$ and a confidence level $c(\cdot)$ we define a function $M_c : \{0, 1\}^* \rightarrow \{0, 1, *\}$ in the following way: $M_c(x) = 1$ ($M_c(x) = 0$) if M accepts (rejects) x with probability at least $c(|x|)$ over its coins, otherwise $M_c(x) = *$. We say that M accepts (rejects) an input x with confidence level $c(|x|)$ if $M_c(x) = 1$ ($M_c(x) = 0$). Otherwise we say that x is undecided.

We say that a machine M *conforms to confidence level* $c(\cdot)$ if for every x , $M_c(x) \in \{0, 1\}$. Given a function $f : \{0, 1\}^* \rightarrow \{0, 1\}$ we say that a machine $M \in \text{PPM}$ decides f with confidence level $c(\cdot)$ if for every x $M_c(x) = f(x)$.

We remark that given a machine $M \in \text{PPM}$ that conforms to some confidence level $c(n) > 1/2 + 1/n$ we can amplify the confidence level and construct a machine $\bar{M} \in \text{PPM}$ that defines the same function relative to confidence level $\bar{c}(n) = 1 - 2^{-n}$.

If we do not explicitly mention the confidence level, its default value is $2/3$.

3. The deterministic case

In this section we prove the first item of Theorem 1.5, that is that $\text{NP} \neq \text{P} \Rightarrow \text{NP} \not\subseteq \text{Pseudo}_{5/6} \text{P}$. The theorem follows from the following lemma that may be of independent interest. Informally, this lemma says that if $\text{NP} \neq \text{P}$ then for any algorithm that fails to solve SAT it is possible to produce three formulae where on one of them the algorithm makes an error.

LEMMA 3.1 (Producing hard instances (deterministic version)). *Assume that $\text{NP} \neq \text{P}$. There is a deterministic procedure R , a polynomial $q(\cdot)$ and a constant d such that the procedure R gets three inputs: integers n , a and a description of a deterministic machine BSAT ; the machine R runs in time $n^{d \cdot a^2}$ and outputs at most three formulae where the length of each formula is either n or $q(n^a)$. Furthermore, if BSAT is an algorithm that on inputs of length n runs in time bounded by n^a (for some constant a) then for infinitely many input lengths n , invoking $R(n, a, \text{BSAT})$ gives a set F of formulae such that there exist $\phi \in F$ with $\text{BSAT}(\phi) \neq \text{SAT}(\phi)$.*

We first observe that the first item of Theorem 1.5 follows from Lemma 3.1.

PROOF OF THEOREM 1.5 FIRST ITEM. We assume that $\text{NP} \neq \text{P}$, and assume for the purpose of contradiction that $\text{NP} \subseteq \text{Pseudo}_{5/6} \text{P}$. By this assumption there exists a deterministic algorithm BSAT that runs in time n^a for some constant a . Furthermore, for any samplable distribution $\mathcal{D} = \{\mathcal{D}_n\}_{n \in \mathbb{N}}$ we have that for large enough n , $\Pr_{x \in \mathcal{D}_n}[\text{BSAT}(x) = \text{SAT}(x)] \geq 5/6$. Let R

be the procedure from Lemma 3.1 and let $q(\cdot)$ and d be the polynomial and the constant guaranteed in the lemma. We consider the following distribution $\mathcal{D} = \{\mathcal{D}_n\}_{n \in \mathbb{N}}$ defined by a sampling algorithm.

Sampling algorithm for \mathcal{D} : On input 1^n we first invoke $R(n, a, \text{BSAT})$. By Lemma 3.1 R outputs at most three formulae of length either n or $q(n^a)$. We ignore formulae of length $q(n^a)$. We then check whether there exists a number n' such that $q((n')^a) = n$. If there exist such an n' , we invoke $R(n', a, \text{BSAT})$. Once again we get at most three formulae with lengths either n' or $q((n')^a) = n$. We ignore the formulae of length n' . At the end of this process we have at most six formulae $B_n = \{x_1, \dots, x_t\}$ for $1 \leq t \leq 6$ where each one is of length n . We now uniformly choose one of these formulae and output it.

Note that each invocation of R takes time at most $n^{d \cdot a^2}$ and therefore the sampling procedure runs in polynomial time. From Lemma 3.1 we have that for infinitely many n , one of the at most three formulae produced by $R(n, a, \text{BSAT})$ is one on which BSAT errs. For each such n , this formula is either of length n or of length $q(n^a)$. Therefore for infinitely many n , B_n contains a formula on which BSAT errs and with probability at least $1/6$ this formula is chosen by $\mathcal{D}(1^n)$. This is a contradiction as BSAT is supposed to be correct on *any* samplable distribution with probability $5/6$ for large enough n . \square

REMARK 3.2 (A deterministic procedure for finding a hard instance). We can prove a stronger result by using a less constructive argument. Consider 6 different deterministic algorithms R_1, \dots, R_6 where for each $1 \leq i \leq 6$, $R_i(1^n)$ runs the procedure defined in the proof, to produce B_n and then outputs the i 'th element in B_n (if such exists). For at least one i , $R_i(1^n)$ produces a formula on which BSAT errs for infinitely many lengths n . Note that whenever R_i outputs such a formula it does it with probability $1/6$!

Thus under the assumption that $NP \neq P$ we can prove a stronger result than the one claimed in Theorem 1.5, that there exist a deterministic algorithm that outputs a hard instance on infinitely many input lengths. Using the terminology of Kabanets (2001) this means that if $NP \neq P$ then $NP \not\subseteq \text{PseudopP}$.

The remainder of this section is devoted to proving Lemma 3.1.

3.1. A search algorithm. Let a be some constant and let BSAT be a deterministic algorithm that runs in time at most m^a on inputs of length m . We define an algorithm SSAT that gets a formula x as input, uses BSAT as an oracle, and can give one of three answers:

- 'yes' and an assignment α that is a proof that x is a satisfiable formula.
- 'no' - that means that BSAT answers 'no' on x .
- "error" and a set F of formulae - taken to mean that BSAT is an incorrect algorithm, and BSAT must be wrong on at least one formula from F .

We now describe the algorithm SSAT. Loosely speaking, SSAT is the standard algorithm that uses BSAT (and the self reducibility of SAT) to conduct a search for a witness. Algorithm SSAT answers that the formula is satisfiable only if the search concludes with a witness. A precise description follows.

The Algorithm SSAT: The input to SSAT is a Boolean formula x over the variables v_1, \dots, v_m and uses an algorithm BSAT as oracle. On input x , SSAT first asks BSAT if $x^0 = x$ is satisfiable, and if BSAT answers 'no', SSAT also answers 'no'. Otherwise, suppose SSAT has so far fixed the partial assignment $\alpha_1, \dots, \alpha_i$ and BSAT claims $x^i = x(\alpha_1, \dots, \alpha_i, v_{i+1}, \dots, v_m)$ is satisfiable. SSAT asks BSAT if x^i is satisfiable when v_{i+1} is set to *false* and when it is set to *true*. If BSAT says none is satisfiable, SSAT declares an error and outputs x^i , $x_0^i = x(\alpha_1, \dots, \alpha_i, 0, v_{i+2}, \dots, v_m)$ and $x_1^i = x(\alpha_1, \dots, \alpha_i, 1, v_{i+2}, \dots, v_m)$. Otherwise, BSAT "claims" at least one of the two possibilities is satisfied, and SSAT sets v_{i+1} accordingly (choosing arbitrarily in the case the two possibilities are satisfied). At the end, SSAT holds a complete assignment $\alpha = \alpha_1, \dots, \alpha_m$ and it checks if it satisfies x . If it does, SSAT outputs 'yes' and the assignment α . Otherwise, it declares an error and outputs the constant formula $x^n = x(\alpha_1, \dots, \alpha_n)$. By padding formulae before feeding them to BSAT we can make sure that all formulae that come up during an execution of SSAT are of the length of the initial input x .

It is useful to sum up the properties of SSAT with the following straightforward lemma (the proof is omitted).

LEMMA 3.3. *Algorithm SSAT runs in polynomial time and furthermore:*

- *If SSAT answers 'yes' on x then x is satisfiable and SSAT outputs an assignment α that satisfies x .*
- *If SSAT answers 'no' on x then BSAT answers 'no' on x .*
- *If SSAT answers 'error' then SSAT outputs a set F of at most three formulae of length identical to that of x such that there is a formula $y \in F$ with $\text{BSAT}(y) \neq \text{SAT}(y)$.*

3.2. Finding incorrect instances. We now describe the procedure R from Lemma 3.1. We obtain as input numbers n , a and a description of a deterministic machine BSAT. We modify BSAT so that it stops after at most m^a steps on inputs of length m . This in turn defines a polynomially related time bound on SSAT.

For every integer n we define an NP statement ϕ_n :

$$\exists_{x \in \{0,1\}^n} [\text{SAT}(x) = 1 \text{ and } \text{SSAT}(x) \neq \text{'yes'}] .$$

Note that indeed there is a circuit of size polynomial in n^a that given a formula x and an assignment α checks whether it is the case that both α satisfies x and $\text{SSAT}(x) \neq \text{'yes'}$. Using the Cook–Levin theorem the procedure R reduces ϕ_n into a formula ϕ'_n of length polynomial in n^a over variables x , α and z (where z is the auxiliary variables added by the reduction) with the property that ϕ'_n is satisfiable if and only if ϕ_n is satisfiable. Furthermore the Cook–Levin reduction also gives that for any triplet (x, α, z) that satisfies ϕ'_n , x satisfies ϕ_n and α is a satisfying assignment for x . We choose $q(\cdot)$ to be a polynomial that is large enough so that $q(n^a)$ is bigger than the length of ϕ'_n . (Note that this can be done for a universal polynomial q that does not depend on n or BSAT and depends only on the efficiency of the Cook–Levin reduction). We then pad ϕ'_n to length $q(n^a)$.

REMARK 3.4. Before we continue with the proof, we want to point out that the use of the statement ϕ_n relies on the fact that the computation of BSAT (and hence SSAT) has a short description as a Boolean formula. In other words, our analysis only applies to an efficient BSAT. This means that when viewed as a reduction, our argument is non-black-box. We refer the reader to Gutfreund & Ta-Shma (2006) for a detailed analysis and discussion about the reduction that we give here and what exactly makes it non-black-box. We want to emphasize that one should not confuse non-black-box with non-relativizing. Indeed our argument does relativize.

The procedure R then runs SSAT on ϕ'_n using BSAT as an oracle. There are three cases:

- SSAT declares an error during the run and outputs three (or one) formulae. In this case the procedure outputs these formulae.
- SSAT outputs 'no'. In this case the procedure outputs ϕ'_n .
- SSAT outputs 'yes' and a satisfying assignment (x, α, z) for ϕ'_n . In particular, $x \in \text{SAT}$ but $\text{SSAT}(x) \neq \text{'yes'}$. The procedure then runs SSAT

on x . There are now only two options (either SSAT declares an error, or answers 'no'):

- SSAT declares an error during the run and outputs three (or one) formulae. In this case the procedure outputs these formulae.
- SSAT outputs 'no'. In this case the procedure outputs x .

3.3. Correctness. The most time consuming step in the description of R is running SSAT on ϕ'_n . Recall that SSAT is an algorithm that runs in time $\text{poly}(n^a)$ on inputs of length n , and we feed it an input ϕ'_n of length $q(n^a) = \text{poly}(n^a)$. Altogether the running time is bounded by $\text{poly}(n^{a^2})$ as required.

Let us consider a modification SSAT' of SSAT that gives a Boolean answer: It answers 'yes' when SSAT answers 'yes' and 'no' when SSAT answers 'no' or 'error'. By our assumption $\text{NP} \neq \text{P}$ and in particular SSAT' does not solve SAT. This means that there are infinitely many input lengths n on which SSAT' makes errors. We show that when R is given n , where n is such an input length then it finds instances on which BSAT is incorrect.

LEMMA 3.5. *For any input length n on which SSAT' doesn't correctly solve SAT, if R is given the triplet (n, a, BSAT) as input, then it outputs at most three formulae such that on at least one of them BSAT makes an error.*

PROOF. Note that SSAT' has one-sided error: It cannot err when it answers 'yes'. Thus, there exists a satisfiable formula x of length n such that $\text{SSAT}'(x) = \text{'no'}$. It follows that ϕ'_n is a satisfiable formula. We now follow the description of the procedure R and show that in all cases it finds instances on which BSAT makes an error. Recall that R runs $\text{SSAT}(\phi'_n)$.

- If SSAT declares an error during the execution on ϕ'_n then by Lemma 3.3, one of the three formulae (of length $q(n^a)$) that SSAT outputs is an error of BSAT.
- If SSAT outputs 'no', then by Lemma 3.3, $\text{BSAT}(\phi'_n) = \text{'no'}$ and thus BSAT makes an error on ϕ'_n .
- If SSAT outputs 'yes', then it also outputs a satisfying assignment (x, α, z) for ϕ'_n and in particular, $x \in \text{SAT}$ but $\text{SSAT}(x) \neq \text{'yes'}$. The procedure R then runs SSAT on x . There are now only two options (either SSAT declares an error, or answers 'no'):

- If SSAT declares an error during the run then by Lemma 3.3 it outputs at most three formulae (of length n) such that on one of them BSAT errs.
- If SSAT outputs 'no' then by Lemma 3.3, $\text{BSAT}(x) = \text{'no'}$. However we know that x is satisfiable and therefore R finds an error of BSAT. \square

This concludes the proof of Lemma 3.1.

REMARK 3.6 (Finding hard instances when assuming $\text{NP} = \text{P}$). *Lemma 3.1 shows that assuming that $\text{NP} \neq \text{P}$, we can find hard instances for any polynomial time algorithm attempting to solve SAT. We remark that in case $\text{NP} = \text{P}$, it is also easy to find hard instances for any polynomial time algorithm that does not solve SAT. This is easily done by using the polynomial time SAT solver to find a witness of a formula that checks the statement “there exists an instance of length n on which the given algorithm and the SAT solver do not agree”. Thus Lemma 3.1 actually holds unconditionally whenever BSAT fails to solve SAT in the worst-case (although for the proof of Theorem 1.5 it is enough to state it the way it is).*

4. The randomized case

In this section we prove the second item of Theorem 1.5, namely that $\text{NP} \neq \text{RP} \Rightarrow \text{NP} \not\subseteq \text{Pseudo}_{97/100} \text{BPP}$.

The overall structure of the proof follows that of the deterministic setting. The theorem follows from the following lemma that is analogous to Lemma 3.1 and may be of independent interest. Informally, this lemma says that if $\text{NP} \neq \text{RP}$ then for any randomized algorithm that fails to solve SAT, it is possible to produce three formulae such that with a good probability, the algorithm makes an error on one of them. It is important to stress that we do not assume that the given randomized machine conforms to some confidence level.

LEMMA 4.1 (Producing hard instances (randomized version)). *Assume that $\text{NP} \neq \text{RP}$. For every constant $c > 1/2$ there is a randomized procedure R , a polynomial $q(\cdot)$ and a constant d such that the procedure R gets three inputs: integers n, a and a description of a randomized machine BSAT; the procedure R runs in time $n^{d \cdot a^2}$ and outputs at most three formulae where the length of each formula is either n or $q(n^a)$. Furthermore, if BSAT is a randomized algorithm that on inputs of length n runs in time bounded by n^a then for infinitely many*

input lengths n , invoking $R(n, a, \text{BSAT})$ gives with probability $1 - 1/n$ a set F of formulae such that there exist $\phi \in F$ with $\text{BSAT}_c(\phi) \neq \text{SAT}(\phi)$.

The proof that the second item of Theorem 1.5 follows from Lemma 4.1 is very similar to that in the previous Section. (Here we also have to take into consideration the coin tosses of BSAT and the $1/n$ error probability of R .)

PROOF OF THEOREM 1.5 SECOND ITEM. We assume that $\text{NP} \neq \text{RP}$, and assume for the purpose of contradiction that $\text{NP} \subseteq \text{Pseudo}_{97/100} \text{BPP}$. By this assumption there exists a randomized algorithm BSAT that runs in time n^a for some constant a . Furthermore, for any samplable distribution $\mathcal{D} = \{\mathcal{D}_n\}_{n \in \mathbb{N}}$ we have that for large enough n , $\Pr_{x \in \mathcal{D}_n, y}[\text{BSAT}(x, y) = \text{SAT}(x)] \geq 97/100$ (here $y \in \{0, 1\}^{\text{poly}(n)}$ are the random coins of BSAT). Let R be the procedure from Lemma 3.1 and let $q(\cdot)$ and d be the polynomial and the constant guaranteed in the lemma. We consider the following distribution $\mathcal{D} = \{\mathcal{D}_n\}_{n \in \mathbb{N}}$ defined by a sampling algorithm.

Sampling algorithm for \mathcal{D} : We choose $c = 51/100$. On input 1^n we first invoke $R(n, a, \text{BSAT})$. By Lemma 4.1, R outputs at most three formulae of length either n or $q(n^a)$. We ignore formulae of length $q(n^a)$. We then check whether there exists a number n' such that $q((n')^a) = n$. If there exist such an n' , we invoke $R(n', a, \text{BSAT})$. Once again we get at most three formulae with lengths either n' or $q((n')^a) = n$. We ignore the formulae of length n' . At the end of this process we have at most six formulae $B_n = \{x_1, \dots, x_t\}$ for $1 \leq t \leq 6$ where each one is of length n . We now uniformly choose one of these formulae and output it.

Note that each invocation of R takes time at most $n^{d \cdot a^2}$ and therefore the sampling procedure runs in polynomial time. From Lemma 3.1 we have that for infinitely many n , with probability at least $1 - 1/n$ one of the at most three formulae produced by $R(n, a, \text{BSAT})$ is a formula y on which $\text{BSAT}_c(y) \neq \text{SAT}(y)$. We call such lengths n *useful*. For each useful n , we consider two events: The first is that $R(n, a, \text{BSAT})$ contains a formula y as above of length n and the second that $R(n, a, \text{BSAT})$ contains a formula y as above of length $q(n^a)$. For each useful n at least one of the events occurs with probability at least $(1 - 1/n)/2 = 1/2 - 1/2n$ (over the coin tosses of R). It follows that for infinitely many n , with probability $1/2 - 1/2n$ the set B_n contains a formula y as above. For each such n , we choose such a formula with probability at least $1/6$. Finally, having y such that $\text{BSAT}_c(y) \neq \text{SAT}(y)$ means that the probability that BSAT answers correctly on y is smaller than c . Therefore with probability

at least $\frac{1}{6} \cdot (\frac{1}{2} - \frac{1}{2n}) \cdot (1 - c) > 3/100$ (over the coin tosses of both \mathcal{D} and BSAT) we have that BSAT fails to compute SAT correctly on the output of \mathcal{D} . \square

REMARK 4.2. *In our proof we do not try to optimize the constants. by using a more careful calculation, the constant 97/100 can be improved. However, we do not know how to get it below 2/3 (see Open Question 6.1).*

The remainder of this section is devoted to proving Lemma 4.1. We assume that $\text{NP} \neq \text{RP}$ and fix some constant $c > 1/2$.

4.1. Using Adelman’s method on BSAT. Given a randomized algorithm BSAT such that for any m and all choices of random coins BSAT runs in time m^a , we transform the algorithm BSAT into an algorithm $\overline{\text{BSAT}}$ by amplification.

The algorithm $\overline{\text{BSAT}}$: When given a formula x of length n , the algorithm $\overline{\text{BSAT}}$ uniformly chooses n^2 independent strings v_1, \dots, v_{n^2} where each of them is of length n^a . For every $1 \leq i \leq n^2$, the algorithm applies $\text{BSAT}(x, v_i)$ and it outputs the majority vote of the answers.

The purpose of this amplification is to use the argument of Adelman (1978) to show that many fixed choices of randomness for $\overline{\text{BSAT}}$ “capture” the behavior of BSAT.

DEFINITION 4.3. *Let n be some integer and $c > 1/2$. We say that a string u of length n^{a+2} is good for BSAT at length n and confidence c if for every x of length n and $b \in \{0, 1\}$:*

$$\overline{\text{BSAT}}(x, u) = b \Rightarrow \text{BSAT}_c(x) \in \{b, *\}.$$

The following straightforward lemma is proven by using similar arguments as in Adelman (1978).

LEMMA 4.4. *Let $1/2 < c \leq 1$ be some constant. For every large enough n , the fraction of strings of length n^{a+2} that are good for BSAT at length n and confidence c is at least $1 - 2^{-n}$.*

PROOF. Fix $x \in \{0, 1\}^n$ such that $\text{BSAT}_c(x) = b$, for $b \in \{0, 1\}$. Let $u = v_1, \dots, v_{n^2}$ be the random coins for $\overline{\text{BSAT}}$. By the Chernoff bound,

$$\Pr_u [\overline{\text{BSAT}}(x, u) = 1 - b] < e^{-\frac{c}{2}n^2(1-\frac{1}{2c})^2} \leq 2^{-2n}.$$

Since there are 2^n strings of length n , by the union bound, for a randomly chosen $u \in \{0, 1\}^{n^{a+2}}$, there exists $x \in \{0, 1\}^n$ such that $\text{BSAT}_c(x) = b$ (for $b \in \{0, 1\}$) but $\overline{\text{BSAT}}(x, u) = 1 - b$, with probability at most 2^{-n} . We conclude that with probability at least $1 - 2^{-n}$, for a randomly chosen $u \in \{0, 1\}^{n^{a+2}}$ it holds that for every x of length n and $b \in \{0, 1\}$:

$$\overline{\text{BSAT}}(x, u) = b \Rightarrow \text{BSAT}_c(x) \in \{b, *\}. \quad \square$$

4.2. A search algorithm. We now define the randomized analog of the search algorithm SSAT from Section 3.1.

The Algorithm SSAT: Given a formula x of length n , the algorithm SSAT uniformly chooses a string $u \in \{0, 1\}^{n^{a+2}}$. From that point on, the algorithm operates exactly in the same way as the version described in Section 3.1 with the exception that whenever the algorithm described there wants to compute $\text{BSAT}(y)$ for some formula y , the new algorithm computes $\overline{\text{BSAT}}(y, u)$. We use the notation $\text{SSAT}(x, u)$ to describe the outcome of SSAT on x when using u as random coins.

It is useful to sum up the properties of SSAT with the following lemma which is analogous to Lemma 3.3.

LEMMA 4.5. *Algorithm SSAT runs in randomized polynomial time. Furthermore, let $1/2 < c < 1$ be some constant and n a large enough integer. Fix some string u of length n^{a+2} that is good for BSAT at length n and confidence level c , then:*

- *If $\text{SSAT}(x, u) = \text{'yes'}$ then x is satisfiable and SSAT outputs an assignment α that satisfies x .*
- *If $\text{SSAT}(x, u) = \text{'no'}$ then $\text{BSAT}_c(x) \in \{0, *\}$.*
- *If $\text{SSAT}(x, u)$ answers 'error' then SSAT outputs a set F of at most three formulae of length identical to that of x and there exist $y \in F$ such that $\text{BSAT}_c(y) \neq \text{SAT}(y)$.*

PROOF. The proof is essentially identical to that of Lemma 3.3 by using the properties of a good u (Definition 4.3).

For the first item note that $\text{SSAT}(x, u)$ answers 'yes' only after it checks that α is a satisfying assignment. For the second item note that $\text{SSAT}(x, u)$

answers 'no' only if $\overline{\text{BSAT}}(x, u)$ answers 'no' on the given input. By Definition 4.3 and the fact that u is good for BSAT of length n , it follows that $\text{BSAT}_c(x) \in \{0, *\}$.

For the third item note that $\text{SSAT}(x, u)$ answers error on two cases: In the first case, $\overline{\text{BSAT}}(\cdot, u)$ claims that some formula is satisfiable while claiming that the two descendent formulae obtained by substituting a variable to zero or one are unsatisfiable and $\text{SSAT}(x, u)$ outputs these three formulae. It follows that on at least one formula, y , of the three $\overline{\text{BSAT}}(y, u) \neq \text{SAT}(y)$. By Definition 4.3 this implies that $\text{BSAT}_c(y) \neq \text{SAT}(y)$. In the second case, $\overline{\text{BSAT}}(\cdot, u)$ "claims" that some formula y (with no variables) has the constant Boolean value "one" while SSAT checks and see that it has "zero". Again by Definition 4.3 it follows that $\text{BSAT}_c(y) \neq \text{SAT}(y)$. In both cases the length of the formulae is identical to that of x because of the way we padded queries to $\overline{\text{BSAT}}$ in the description of SSAT . \square

4.3. Finding incorrect instances. For every integer n and $u \in \{0, 1\}^{n^{a+2}}$ we define an NP statement $\phi_{n,u}$:

$$\phi_{n,u} = \exists_{x \in \{0,1\}^n} [\text{SAT}(x) = 1 \text{ and } \text{SSAT}(x, u) \neq \text{'yes'}].$$

Note that indeed there is a circuit of size polynomial in n^a that given a formula x and an assignment α checks whether it is the case that both α satisfies x and $\text{SSAT}(x, u) \neq \text{'yes'}$. Using the Cook–Levin theorem the procedure R reduces $\phi_{n,u}$ into a formula $\phi'_{n,u}$ of length polynomial in n^a over variables x , α and z (where z is the auxiliary variables added by the reduction) with the property that $\phi'_{n,u}$ is satisfiable if and only if $\phi_{n,u}$ is satisfiable. Furthermore the Cook–Levin reduction also gives that for any triplet (x, α, z) that satisfies $\phi'_{n,u}$, x satisfies $\phi_{n,u}$ and α is a satisfying assignment for x . We choose $q(\cdot)$ to be a polynomial that is large enough so that $q(n^a)$ is bigger than the length of $\phi'_{n,u}$. (Note that this can be done for a universal polynomial q that does not depend on n, u or BSAT and depends only on the efficiency of the Cook–Levin reduction). We then pad $\phi'_{n,u}$ to length $q(n^a)$.

The procedure R chooses at random strings $u' \in \{0, 1\}^{q(n^a)^{a+2}}$ and $u \in \{0, 1\}^{n^{a+2}}$. It then runs $\text{SSAT}(\phi'_{n,u}, u')$. There are three cases:

- SSAT declares an error during the run and outputs three (or one) formulae. In this case the procedure outputs these formulae.
- SSAT outputs 'no'. In this case the procedure outputs $\phi'_{n,u}$.

- SSAT outputs 'yes' and a satisfying assignment (x, α, z) for $\phi'_{n,u}$.

The procedure then runs $\text{SSAT}(x, u)$. There are three cases:

- SSAT declares an error during the run and outputs three (or one) formulae. In this case the procedure outputs these formulae.
- SSAT outputs 'no'. In this case the procedure outputs x .
- SSAT outputs 'yes'. In this case the procedure fails.

4.4. Correctness. The most time consuming step in the description of R is running SSAT on $\phi'_{n,u}$. Recall that SSAT is an algorithm that runs in time $\text{poly}(n^a)$ on inputs of length n , and we feed it an input $\phi'_{n,u}$ of length $q(n^a) = \text{poly}(n^a)$. Altogether the running time is bounded by $\text{poly}(n^{a^2})$ as required.

We now prove that with a good probability the procedure does not fail. We first prove:

LEMMA 4.6. *Suppose R chooses u, u' such that:*

- u is good for BSAT at length n , and,
- The sentence $\phi_{n,u}$ is TRUE, and,
- u' is good for BSAT at length $q(n)$.

Then, R outputs a set F of at most three formulae such that there exists $y \in F$ such that $\text{BSAT}_c(y) \neq \text{SAT}(y)$.

PROOF. We know that u' is good for BSAT at length $q(n)$ and that $\phi'_{n,u}$ is satisfiable. We are now in a similar position to the deterministic case. If $\text{SSAT}(\phi'_{n,u}, u')$ declares an error, then by Lemma 4.5 one of the three formulae (of length $q(n^a)$) that SSAT outputs is a formula y such that $\text{BSAT}_c(y) \neq \text{SAT}(y)$. If SSAT outputs 'no', then by Lemma 4.5, $\text{BSAT}_c(\phi'_{n,u}) \in \{*, \text{'no'}\}$ and thus $\text{BSAT}_c(\phi'_{n,u}) \neq \text{SAT}(\phi'_{n,u})$.

We are left with $\text{SSAT}(\phi'_{n,u}, u') = \text{'yes'}$. In such a case SSAT outputs a satisfying assignment (x, α, z) for $\phi'_{n,u}$, and in particular $\text{SAT}(x) = 1$ but $\text{SSAT}(x, u) \neq \text{'yes'}$. There are now only two options: either $\text{SSAT}(x, u)$ declares an error, or answers 'no'. If SSAT declares an error during the run, then by Lemma 4.5 (and because u is good for BSAT at length n) it outputs a set of at most three formulae (of length n) such that one of them, y , satisfies $\text{BSAT}_c(y) \neq \text{SAT}(y)$. If $\text{SSAT}(x, u)$ outputs 'no' then by Lemma 4.5, $\text{BSAT}_c(x) \in \{*, \text{'no'}\}$. However, we know that x is satisfiable and therefore $\text{BSAT}_c(x) \neq \text{SAT}(x)$. \square

We know that the probability u or u' are not good for BSAT at the appropriate lengths is negligible. We now turn for the remaining condition:

LEMMA 4.7. *Assume $NP \neq RP$. Then, for infinitely many n , except for probability $\frac{1}{2n}$, for a random $u \in \{0, 1\}^{n^{a+2}}$ we have that $\phi_{n,u}$ is TRUE.*

PROOF. Assume not. I.e., except for finitely many n , with probability at least $\frac{1}{2n}$ a random $u \in \{0, 1\}^{n^{a+2}}$ has the property that $\phi_{n,u}$ is FALSE. That is, $\forall x \in \{0, 1\}^n$ [$SAT(x) = 1 \Rightarrow SSAT(x, u) = \text{'yes'}$]. As we always have $SSAT(x, u) = \text{'yes'} \Rightarrow SAT(x) = 1$, we conclude that for all $x \in \{0, 1\}^n$, $SSAT(x, u) = SAT(x)$. In particular SSAT is an RP algorithm with success probability at least $\frac{1}{2n}$, and therefore $NP \subseteq RP$. A contradiction. \square

Altogether, this shows that the fraction of pairs u, u' on which R does not find a hard instance is at most $2^{-n} + 2^{-q(n)} + \frac{1}{2n} \leq \frac{1}{n}$ for large enough n as required. This concludes the proof of Lemma 4.1.

We mention that similar (but more careful) arguments from Remark 3.6 can show that the lemma holds unconditionally whenever BSAT fails to solve SAT in the worst-case.

5. A worst-case to average-case reduction for distributional problems

In this section we prove Theorem 1.6. Namely, we show how to swap the quantifiers and get a single (simple to describe) distribution on SAT instances that is samplable in quasi-polynomial time, and every probabilistic polynomial-time algorithm errs on it with non-negligible probability (unless $NP = RP$).

PROOF OF THEOREM 1.6. Let \mathcal{M}_k be the set of all probabilistic Turing machines upto the k 'th machine, under a standard enumeration of Turing machines. We define the distribution $D = \{D_n\}$ by its generating algorithm: to generate instances of length n , choose uniformly a machine M from $\mathcal{M}_{3 \cdot s(n)/100}$. Run M for $f(n)$ steps on the input 1^n (providing the randomness it needs). If M hasn't halted, output 0^n . Otherwise let x be the output of M . Then pad or trim x to be of length n and output it.

Now assume $NP \neq RP$. We show $(SAT, D) \notin \text{Avg}_{1-1/s(n)}\text{BPP}$. Let A be a probabilistic polynomial-time algorithm trying to solve SAT. By Theorem 1.5, there exists a polynomial time sampler R that samples hard instances for A with a constant probability (i.o.). Let $p(n)$ be R 's running time. Let n_0 be such that for every $n \geq n_0$, $R \in \mathcal{M}_{3 \cdot s(n)/100}$ and $f(n) \geq p(n)$.

There are infinitely many input lengths $n \geq n_0$ for which A errs with probability greater than $3/100$ over instances sampled by $R(1^n)$. Let n_1 be such an input length. With probability at least $100/(3 \cdot s(n_1))$, D_{n_1} picks the machine R . It then runs R on 1^{n_1} for at least $p(n_1)$ steps, and because $p(n_1) < f(n_1)$ R halts, and with probability greater than $3/100$ outputs an instance on which A errs. Overall, the probability (over the instances and A 's internal coins) that A errs on D_{n_1} is at least $1/s(n_1)$ as desired. \square

6. Discussion and open problems

6.1. On standard worst-case to average-case reductions for NP. The qualitative difference between hardness against average classes and hardness against pseudo classes is whether the samplable distribution can be stronger than the polynomial time algorithm and in particular simulate it (as in the pseudo classes) or not (as in the average classes). We believe this is a very fundamental difference. Indeed in the proof of Theorem 1.5, the samplable distribution runs the algorithm. We therefore believe that our techniques are not sufficient for solving Open Question 1.4.

A worst-case to average-case reduction is a mapping from a language L to a language L' , such that for every efficient algorithm A' that solves L' well on the average, there is an efficient algorithm A (that uses A') that solves L in the worst-case. As we mentioned in the introduction, there are works that show that certain classes of reductions cannot establish worst-case to average-case connections for NP-complete languages (under Levin's notion). Specifically, Viola (2004) shows that efficient reductions that only make a black-box use of the language L and the algorithm A' do not exist (unconditionally). Bogdanov & Trevisan (2003) (improving on Feigenbaum & Fortnow (1993)) show that reductions that start from L that is NP-complete, where A uses A' as a black-box and asks it only non-adaptive queries do not exist (unless the polynomial-time hierarchy collapses). We want to point out that our reduction is non-black-box both in L (we use the downwards self-reducibility of SAT), and in A' (we use the fact that BSAT can be computed by an efficient algorithm, and in particular we use the code of this algorithm). It would be interesting to know whether reductions that are non-black-box both in L and A' are necessary to prove a worst-case to average-case reduction for PseudoBPP as in Theorem 1.5 (in contrast to AvgBPP where the negative results of Bogdanov & Trevisan (2003); Feigenbaum & Fortnow (1993); Viola (2004) apply).

6.2. Hardness amplification. A problem that is related (in fact complements) worst-case to average-case reductions, is the problem of hardness am-

plification. That is, whether the existence of a function that is mildly hard (i.e., every algorithm errs with probability at least $1/\text{poly}(n)$ over some samplable distribution on the inputs) implies the existence of a function that is very hard (i.e., every algorithm errs with probability almost half, and therefore is not much better than a coin toss). Here, in contrast to the problem of worst-case to average-case reductions there are many positive results for average classes. It is known that with respect to the uniform distribution (and by Impagliazzo & Levin (1990), it is enough to consider this distribution) hardness amplification can be done for various complexity classes and models of computations and in particular, can be done for functions in EXP and in NP (with various parameters) where the hardness is measured both against uniform and non-uniform classes Babai *et al.* (1993); Healy *et al.* (2006); Impagliazzo & Wigderson (1997); O’Donnell (2004); Sudan *et al.* (2001); Trevisan (2003, 2005); Trevisan & Vadhan (2006); Yao (1982).

Our worst-case to average-case reduction only gives a mildly hard function. One way to improve this would be to show hardness amplification for pseudo classes. We do not know how to do that. In its strongest form, this open question can be stated as:

OPEN QUESTION 6.1. Does $NP \not\subseteq Pseudo_{1-n^{-1}} BPP$ imply $NP \not\subseteq Pseudo_{1/2+n^{-d}} BPP$ for every constant $d \geq 0$?

6.3. Program checking. Suppose that someone claims that he has an efficient algorithm for SAT. Can we automatically check whether the algorithm is correct? For simplicity let’s concentrate on the case that the given algorithm is a search algorithm (this is without loss of generality by the search to decision reduction). Our results show that if $NP \neq RP$ then for infinitely many input lengths we can generate a formula that is satisfiable but the algorithm answers that it isn’t. Nevertheless, when our procedure outputs a formula we cannot be sure that it has this property (it may be the case that the algorithm correctly solves SAT or that we don’t succeed on the given input length). The problem is that we cannot verify that the formula is satisfiable. An interesting open problem suggested to us by Adam Smith is to come up with a “dream-breaker”. This is a procedure that outputs a satisfiable formula *together with a satisfying assignment* on which the given algorithm fails. This allows to verify that the given algorithm errs on the generated formula. We remark that dream-breakers exist if one way functions exist because we can test whether the given algorithm inverts a one-way function on a random input. An interesting open problem is to construct dream-breakers from the assumption that NP is hard on the worst case.

The question whether dream-breakers exist is related to the large body of research about program checking. This notion was formalized by Blum & Kannan (1995). There are two important differences between the program checkers of Blum & Kannan (1995) and the dream-breakers that we consider above. First, in the model of Blum & Kannan (1995), the checker only has a black-box access to the program being checked, and in particular it does not rely on the efficiency of the program. We on the other hand allow the checker to look at the description of the program. In this sense the program checkers of Blum & Kannan (1995) are stronger. On the other hand, Blum & Kannan (1995) only aims to check the program on a given instance, while we aim at checking whether the program solves an NP-complete problem on every instance (of a given length). Micali (2000) considered a model of checkers that is in between. Specifically, his checkers have non-black-box access to the program being checked (and in particular they can rely on the fact that the program is efficient), but the aim is still to check whether the program is correct on a given instance.⁴ In Micali (2000) it was shown that if a *coNP*-complete problem has a non-interactive *computationally sound* proof system, then there are checkers for NP-complete problems in his model of program checking. Whether there are checkers for NP-complete problems in the model of Blum & Kannan (1995) is a long standing open problem (even under plausible assumptions).

6.4. Subsequent work. Following the publication of the conference version of this paper Gutfreund *et al.* (2005), there has been some work that addressed most of the issues we raised in this section.

Gutfreund & Ta-Shma (2006) used the results of this paper to prove a conditional worst-case to average-case reduction under the standard notion of average-case complexity (i.e., Definition 1.2). Specifically they show under a weak derandomization assumption that if NP is worst-case hard for BPP, then nondeterministic quasi-polynomial time is average-case hard for BPP.

Also in Gutfreund & Ta-Shma (2006), it is shown that a generalization of the argument of Bogdanov & Trevisan (2003) rules out the possibility to prove Theorem 1.6 (and hence Theorem 1.5) via black-box and non-adaptive reductions, under the assumption that there is a language in *coNP* that cannot be decided by a family of quasi-polynomial size nondeterministic circuits. Our reduction can be done non-adaptively, by replacing the standard search to decision reduction in the proof of Lemma 4.1 by a non-adaptive reduction of Ben-David *et al.* (1990). Thus the techniques we develop here suggest a way to

⁴The model of Micali (2000) has in addition some efficiency requirements that we ignore in this discussion.

bypass the limitations of Bogdanov & Trevisan (2003); Feigenbaum & Fortnow (1993), and highlights non-black-box reductions as the direction to do that.

Atserias (2006) gives a non-uniform version of Theorem 1.5. That is, he shows how to generate hard instances for a given small circuit by using the circuit only as an oracle, and without looking at its description. This is in contrast to our proof of Lemma 4.1, where the procedure R must have access to the code of the algorithm BSAT. Still, his proof relies on the fact that the circuit is small, so his argument is again non-black-box.

Finally, Gutfreund (2006) makes a progress towards solving Open Question 6.1, by proving:

THEOREM 6.2. *For every constant $d > 0$,*

$$NP \not\subseteq BPP \Rightarrow P_{\parallel}^{NP} \not\subseteq Pseudo_{1/2+n-d} BPP.$$

Here P_{\parallel}^{NP} is the class of languages decidable by deterministic polynomial-time TM's making non-adaptive NP-oracle calls.

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